# ARTIFICIAL INTELLIGENCE AND GOVERNMENTS: THE GOOD, THE BAD, AND THE UGLY

Martin Beraja (MIT)

AEA Continuing Education, January 2023

- ► AI is a multi-faceted technology, with different features and uses
- ► Has brought opportunities and challenges, raising questions about the role of gov'ts

- ► AI is a multi-faceted technology, with different features and uses
- ► Has brought opportunities and challenges, raising questions about the role of gov'ts
  - 1. The Good: Al is a data-intensive technology. New gov't policies to foster innovation? "Data-intensive innovation and the state: Evidence from Al firms in China" (with Yang and Yuchtman)

- ► AI is a multi-faceted technology, with different features and uses
- ► Has brought opportunities and challenges, raising questions about the role of gov'ts
  - 1. The Good: Al is a data-intensive technology. New gov't policies to foster innovation? "Data-intensive innovation and the state: Evidence from Al firms in China" (with Yang and Yuchtman)
  - 2. The Bad: AI is an automation technology. Should gov'ts tax it and slow down adoption? *"Inefficient automation"* (with Zorzi)

- ► AI is a **multi-faceted** technology, with different features and uses
- ► Has brought opportunities and challenges, raising questions about the role of gov'ts
  - 1. The Good: AI is a data-intensive technology. New gov't policies to foster innovation? "Data-intensive innovation and the state: Evidence from AI firms in China" (with Yang and Yuchtman)
  - 2. The Bad: AI is an automation technology. Should gov'ts tax it and slow down adoption? *"Inefficient automation"* (with Zorzi)
  - 3. The Ugly: AI is a surveillance technology. Gov't misuse for repression and social control? *"AI-tocracy"* (with Kao, Yang and Yuchtman) *"Exporting the surveillance state via trade in AI"* (with Kao, Yang and Yuchtman)

# 1. The Good: Access to Government Data as Innovation Policy

2. The Bad: Inefficient Automation

3. The Ugly: AI-tocracy

- Much focus on how data collected by private firms shapes AI innovation (Agrawal et al., 2019; Jones and Tonetti, 2020)
- > Yet, throughout history, states have also collected massive quantities of data
- ► The state has a large role in many areas
  - Public security, health care, education, basic science...

- Much focus on how data collected by private firms shapes AI innovation (Agrawal et al., 2019; Jones and Tonetti, 2020)
- > Yet, throughout history, states have also collected massive quantities of data
- ► The state has a large role in many areas
  - Public security, health care, education, basic science...

## Can access to government data stimulate commercial AI innovation?

## DATA-INTENSIVE INNOVATION AND THE STATE: EVIDENCE FROM AI FIRMS IN CHINA

A common way in which firms access to gov't data is by providing services to the state

## DATA-INTENSIVE INNOVATION AND THE STATE: EVIDENCE FROM AI FIRMS IN CHINA

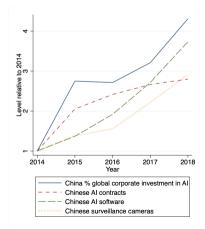
A common way in which firms access to gov't data is by providing services to the state

- Algo's trained on video of faces from many angles
- Government units collect this data through their surveillance apparatus, and contract AI firms

A common way in which firms access to gov't data is by providing services to the state

- Algo's trained on video of faces from many angles
- Government units collect this data through their surveillance apparatus, and contract AI firms

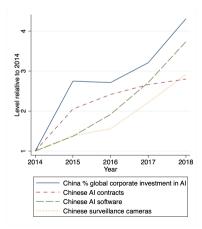




A common way in which firms access to gov't data is by providing services to the state

- Algo's trained on video of faces from many angles
- Government units collect this data through their surveillance apparatus, and contract AI firms
- Firms gaining access to this data use it to train algorithms and provide gov't services
- If gov't data or algorithms are sharable across uses, they can be used to develop commercial AI (e.g., a facial recognition platform for retail stores)





## DATA 1: LINKING AI FIRMS TO GOVT. CONTRACTS

- 1. Identify all facial recognition AI firms
  - 7,837 firms
  - Two sources: Tianyancha (People's Bank of China) and PitchBook (Morningstar)

## DATA 1: LINKING AI FIRMS TO GOVT. CONTRACTS

#### 1. Identify all facial recognition AI firms

- 7,837 firms
- Two sources: Tianyancha (People's Bank of China) and PitchBook (Morningstar)

#### 2. Obtain universe of government contracts

- 2,997,105 contracts
- Source: Chinese Govt. Procurement Database (Ministry of Finance)

## DATA 1: LINKING AI FIRMS TO GOVT. CONTRACTS

- 1. Identify all facial recognition AI firms
  - 7,837 firms
  - Two sources: Tianyancha (People's Bank of China) and PitchBook (Morningstar)
- 2. Obtain universe of government contracts
  - 2,997,105 contracts
  - Source: Chinese Govt. Procurement Database (Ministry of Finance)
- 3. Link government buyers to AI suppliers
  - 10,677 AI contracts issued by public security arms of government (e.g., local police department)



#### Registered with Min. of Industry and Information Technology

#### Categorize by intended customers (with RNN model using tensorflow):

- 1. **Commercial:** e.g., visual recognition system for smart retail;
- 2. Government: e.g., smart city real time monitoring system on main traffic routes;
- 3. General: e.g., a synchronization method for multi-view cameras based on FPGA chips.

# Within AI public security contracts: variation in the data collection capacity of the public security agency's local surveillance network

- 1. Identify non-AI contracts: police department purchases of street cameras
- 2. Measure quantity of advanced cameras in a prefecture at a given time
- 3. Categorize public security contracts as coming from "high" or "low" camera capacity prefectures

#### Regional variation in contracts



#### Empirical strategy

Triple diff: software releases before and after firm receives 1st data-rich contract (relative to data-scarce)

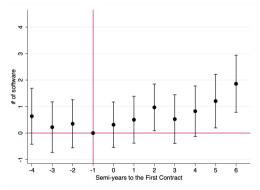
$$y_{it} = \sum_{T} \beta_{1T} T_{it} \mathsf{Data}_i + \sum_{T} \beta_{2T} T_{it} + \alpha_t + \gamma_i + \sum_{T} \beta_{3T} T_{it} X_i + \epsilon_{it}$$

- $T_{it}$ : 1 if T semi-years before/since firm *i*'s 1st contract
- **Data**<sub>i</sub>: 1 if firm *i* receives "data rich" contract
- X<sub>i</sub> pre-contract controls: age, size, and software prod

#### Regional variation in contracts



#### Cumulative commercial software releases



Magnitude: 2 new products over 3 years

# 1. The Good: Access to Government Data as Innovation Policy

2. The Bad: Inefficient Automation

3. The Ugly: AI-tocracy

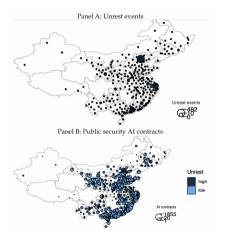
- As a technology of prediction, gov'ts may use AI for repression and social control (Zuboff, 2019; Tirole, 2021; Acemoglu, 2021)
- ► Facial recognition AI, in particular, is a technology of **surveillance** (and dual-use)

- As a technology of prediction, gov'ts may use AI for repression and social control (Zuboff, 2019; Tirole, 2021; Acemoglu, 2021)
- ► Facial recognition AI, in particular, is a technology of **surveillance** (and dual-use)

## Evidence from China?

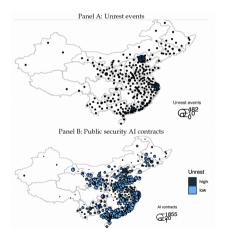
## AI-TOCRACY

## Unrest and gov't procurement of AI

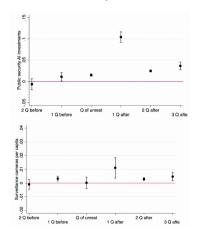


AI-TOCRACY

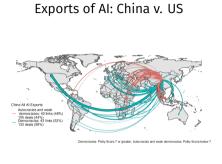
#### Unrest and gov't procurement of AI



Unrest  $\longrightarrow$  Gov't buys AI and cameras



## EXPORTING THE SURVEILLANCE STATE VIA TRADE IN AI





Democracies: Polity Score 7 or greater, Autocracies and weak democracies: Polity Score below 7

## EXPORTING THE SURVEILLANCE STATE VIA TRADE IN AI

# Orem AN Electric Microsoft and With (HP) 10 des (Hp) 10 des (Hp) 10 des (Hp)

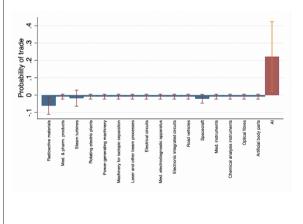
Exports of AI: China v. US

Democracies: Polity Score 7 or greater, Autocracies and weak democracies: Polity Score below 7



Democracies: Polity Score 7 or greater, Autocracies and weak democracies: Polity Score below 7

# Autocracies and weak democracies are more likely to import Al from China



# 1. The Good: Access to Government Data as Innovation Policy

# 2. The Bad: Inefficient Automation

3. The Ugly: AI-tocracy

#### > Past automation (robots) has displaced workers and lowered their earnings

Acemoglu and Restrepo, 2020, 2022; Humlum, 2021

## Past automation (robots) has displaced workers and lowered their earnings Acemoglu and Restrepo, 2020, 2022; Humlum, 2021

- Two economic arguments for slowing down automation based on:
  - 1. Equity considerations (Guerreiro et al, 2022; Costinot and Werning, 2022)
  - 2. Efficiency considerations (Beraja and Zorzi, 2023)

## Past automation (robots) has displaced workers and lowered their earnings Acemoglu and Restrepo, 2020, 2022; Humlum, 2021

► Two economic arguments for slowing down automation based on:

- 1. Equity considerations (Guerreiro et al, 2022; Costinot and Werning, 2022)
- 2. Efficiency considerations (Beraja and Zorzi, 2023)

Are these arguments as strong for AI (e.g., LLMs) as they were for robots?

## Continuous time $t \ge 0$

## Continuous time $t \ge 0$

Occupations

#### Continuous time $t \ge 0$

### Occupations

h = A (degree  $\alpha \ge 0$ ) or h = N

### Continuous time $t \ge 0$

#### Occupations

h = A (degree  $\alpha \ge 0$ ) or h = N

$$y^{A}= extsf{F}\left(\mu^{A},lpha
ight)$$
 ,  $y^{N}= extsf{F}^{\star}\left(\mu^{N}
ight)\equiv extsf{F}\left(\mu^{N},0
ight)$ 

## Continuous time $t \ge 0$

#### Occupations

h = A (degree  $\alpha \ge 0$ ) or h = N

$$\mathbf{y}^{\mathrm{A}}=\mathbf{F}\left(\mu^{\mathrm{A}},\alpha
ight)$$
 ,  $\mathbf{y}^{\mathrm{N}}=\mathbf{F}^{\star}\left(\mu^{\mathrm{N}}
ight)\equiv\mathbf{F}\left(\mu^{\mathrm{N}},0
ight)$ 

Final good producer

$$G^{\star}\left(\boldsymbol{\mu}^{\mathsf{A}},\boldsymbol{\mu}^{\mathsf{N}};\boldsymbol{\alpha}\right)\equiv G\left(\left\{\boldsymbol{y}^{\mathsf{h}}\right\}\right)-\mathcal{C}\left(\boldsymbol{\alpha}\right)$$

#### Continuous time $t \geq 0$

#### Occupations

h = A (degree  $\alpha \ge 0$ ) or h = N

$$\mathbf{y}^{\mathrm{A}}=\mathbf{F}\left(\mu^{\mathrm{A}},\alpha
ight)$$
 ,  $\mathbf{y}^{\mathrm{N}}=\mathbf{F}^{\star}\left(\mu^{\mathrm{N}}
ight)\equiv\mathbf{F}\left(\mu^{\mathrm{N}},0
ight)$ 

Final good producer

$$G^{\star}\left(\mu^{A},\mu^{N};\alpha\right)\equiv G\left(\left\{y^{h}\right\}\right)-\mathcal{C}\left(\alpha\right)$$

## Automation

 $\partial_{\mathsf{A}} G^{\star}\left(\mu^{\mathsf{A}},\mu^{\mathsf{N}};\pmb{lpha}
ight)\downarrow \mathrm{in}\;\pmb{lpha}\;(\mathrm{labor-displacing})$ 

 $G^{\star}\left(\mu^{\mathsf{A}},\mu^{\mathsf{N}};\pmb{\alpha}
ight)$  concave in  $\alpha$  (costly)

#### Continuous time $t \ge 0$

#### Occupations

h = A (degree  $\alpha \ge 0$ ) or h = N

 $y^{\!\!A}=\mu^{\!\!A}+lpha$  ,  $y^{\!\!N}=\mu^{\!\!N}$ 

Final good producer

$$G^{\star}\left(\mu^{A},\mu^{N};\alpha\right) \equiv \left[\left(\alpha+\mu^{A}\right)^{\frac{\nu-1}{\nu}}+\left(\mu^{N}\right)^{\frac{\nu-1}{\nu}}\right]^{\frac{\nu}{\nu-1}}-\mathcal{C}\left(\alpha\right)$$

#### Automation

 $\partial_{\mathsf{A}}G^{\star}\left(\mu^{\mathsf{A}},\mu^{\mathsf{N}};\pmb{\alpha}
ight)\downarrow\mathsf{in}\;\pmb{\alpha}\;(\mathsf{labor-displacing})$ 

 $G^{\star}\left(\mu^{A},\mu^{N};\pmb{lpha}
ight)$  concave in lpha (costly)

Continuous time  $t \ge 0$ 

#### Occupations

h = A (degree  $\alpha \ge 0$ ) or h = N

$$\mathbf{y}^{\mathrm{A}}=\mathbf{F}\left(\mu^{\mathrm{A}},\alpha
ight)$$
 ,  $\mathbf{y}^{\mathrm{N}}=\mathbf{F}^{\star}\left(\mu^{\mathrm{N}}
ight)\equiv\mathbf{F}\left(\mu^{\mathrm{N}},0
ight)$ 

Final good producer

$$G^{\star}\left(\mu^{A},\mu^{N};\alpha\right)\equiv G\left(\left\{y^{h}\right\}\right)-\mathcal{C}\left(\alpha\right)$$

#### Automation

 $\partial_{\mathsf{A}} \mathsf{G}^{\star} \left( \mu^{\mathsf{A}}, \mu^{\mathsf{N}}; \alpha \right) \downarrow \operatorname{in} \alpha$  (labor-displacing)

 $G^{\star}\left(\mu^{A},\mu^{N};\pmb{lpha}
ight)$  concave in lpha (costly)

Profit maximization

$$\max_{\alpha\geq 0}\int_{0}^{+\infty}Q_{t}\Pi_{t}\left(\alpha\right)dt$$

$$\Pi_{t}(\alpha) \equiv \max_{\mu^{A}, \mu^{N} \ge 0} G^{\star}\left(\mu^{A}, \mu^{N}; \alpha\right) - \mu^{A} W_{t}^{A} - \mu^{N} W_{t}^{N}$$

$$U_0 = \int \exp\left(-\rho t\right) \frac{c_t^{1-\sigma}}{1-\sigma} dt$$

$$U_0 = \int \exp\left(-\rho t\right) \frac{c_t^{1-\sigma}}{1-\sigma} dt$$

# Initial allocation

$$U_0 = \int \exp\left(-\rho t\right) \frac{c_t^{1-\sigma}}{1-\sigma} dt$$

Initial allocation

Budget constraint

$$da_t^h = \left[\mathcal{Y}_t^{h,\star} + r_t a_t^h - c_t^h\right] dt$$

WORKERS

#### Preferences

$$U_0 = \int \exp\left(-\rho t\right) \frac{c_t^{1-\sigma}}{1-\sigma} dt$$

Initial allocation

$$\left(\mu_{t}^{\text{A}},\mu_{t}^{\text{N}}
ight) egin{cases} = 1/2 & ext{in } t=0 \\ & & \\$$

Budget constraint

$$da_t^h = \left[\mathcal{Y}_t^{h,\star} + r_t a_t^h - c_t^h\right] dt$$

# Two frictions

1. Reallocation (neoclassical)

$$U_0 = \int \exp\left(-\rho t\right) \frac{c_t^{1-\sigma}}{1-\sigma} dt$$

### Initial allocation

Budget constraint

$$da_t^h = \left[\mathcal{Y}_t^{h,\star} + r_t a_t^h - c_t^h\right] dt$$

# Two frictions

- 1. Reallocation (neoclassical)
  - Random opportunities arrive at rate  $\lambda$

$$U_0 = \int \exp\left(-\rho t\right) \frac{c_t^{1-\sigma}}{1-\sigma} dt$$

### Initial allocation

Budget constraint

$$da_t^h = \left[\mathcal{Y}_t^{h,\star} + r_t a_t^h - c_t^h\right] dt$$

## Two frictions

- 1. Reallocation (neoclassical)
  - Random opportunities arrive at rate  $\lambda$
  - Unempl. / retrain. exit at rate  $\kappa$

$$U_0 = \int \exp\left(-\rho t\right) \frac{c_t^{1-\sigma}}{1-\sigma} dt$$

## Initial allocation

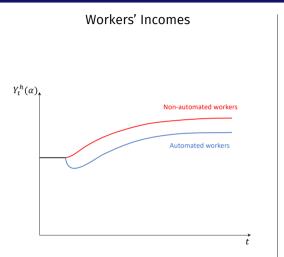
Budget constraint

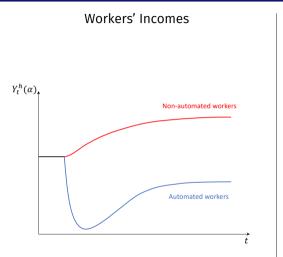
$$da_t^h = \left[\mathcal{Y}_t^{h,\star} + r_t a_t^h - c_t^h\right] dt$$

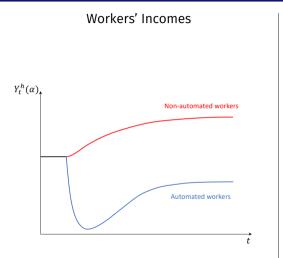
# Two frictions

- 1. Reallocation (neoclassical)
  - Random opportunities arrive at rate  $\lambda$
  - Unempl. / retrain. exit at rate  $\kappa$
- 2. Borrowing

 $a_t^h \geq \underline{a}$  for some  $\underline{a} \leq 0$ 



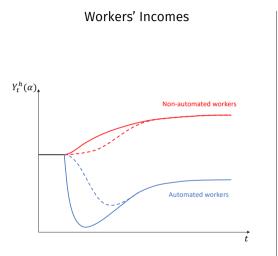




Ricardian workers (ample savings, borrow easily)

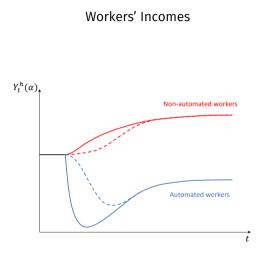
$$\mathcal{L}_{t}^{h}=eta_{t} imes\int_{0}^{\infty}e^{-\int_{0}^{\mathrm{s}}r_{\mathrm{v}}d\mathrm{v}}\mathcal{Y}_{\mathrm{s}}^{h}\left(lpha
ight)d\mathrm{s}$$

▶ Non-auto. better-off; Auto. worse-off



Ricardian workers (ample savings, borrow easily)

- ► Non-auto. better-off; Auto. worse-off
- Equity rationale for taxing automation
   Permanent income redistribution



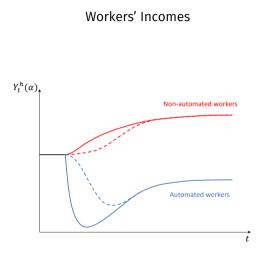
Ricardian workers (ample savings, borrow easily)

$$c_{t}^{h}=eta_{t} imes\int_{0}^{\infty}e^{-\int_{0}^{s}r_{\mathrm{v}}d\mathrm{v}}\mathcal{Y}_{\mathrm{s}}^{h}\left(lpha
ight)d\mathrm{s}$$

- ► Non-auto. better-off; Auto. worse-off
- Equity rationale for taxing automation
   Permanent income redistribution

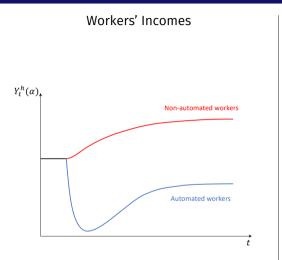
# But firm automation is efficient

Maximize output PDV. Income timing irrelevant



Ricardian workers (ample savings, borrow easily)

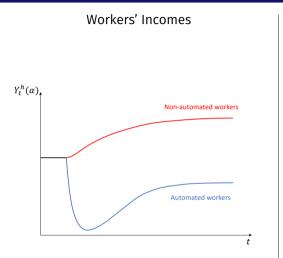
- ► Non-auto. better-off; Auto. worse-off
- Equity rationale for taxing automation
   Permanent income redistribution
- But firm automation is efficient
   Maximize output PDV. Income timing irrelevant
- In practice, workers may be financially vulnerable...



HtM workers (no savings, cannot borrow)

 $c_{t}^{h}=\mathcal{Y}_{t}^{h}\left(\alpha\right)$ 

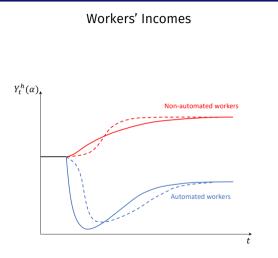
• Timing of  $\mathcal{Y}_t^h$  matters. Not just PDV



HtM workers (no savings, cannot borrow)

 $c_{t}^{h}=\mathcal{Y}_{t}^{h}\left(\alpha\right)$ 

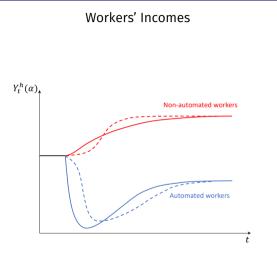
- Timing of  $\mathcal{Y}_t^h$  matters. Not just PDV
- Firms fail to internalize that automation lowers *Y*<sup>Auto</sup><sub>t</sub> early on



HtM workers (no savings, cannot borrow)

 $c_{t}^{h}=\mathcal{Y}_{t}^{h}\left(\alpha\right)$ 

- Timing of  $\mathcal{Y}_t^h$  matters. Not just PDV
- Firms fail to internalize that automation lowers *Y*<sup>Auto</sup><sub>t</sub> early on
- Efficiency rationale for taxing autom. As firms and workers disagree on how they value income over time



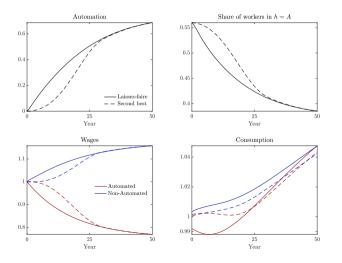
HtM workers (no savings, cannot borrow)

 $c_{t}^{h}=\mathcal{Y}_{t}^{h}\left(\alpha\right)$ 

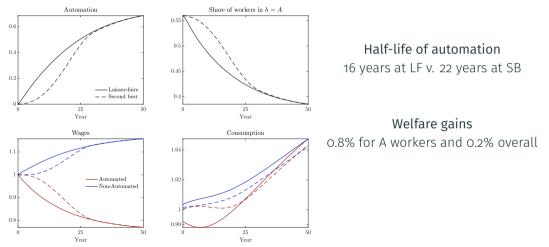
- Timing of  $\mathcal{Y}_t^h$  matters. Not just PDV
- Firms fail to internalize that automation lowers *Y*<sup>Auto</sup><sub>t</sub> early on
- Efficiency rationale for taxing autom. As firms and workers disagree on how they value income over time
- ► No Efficiency v. Equity trade-off

Adds: gradual autom. + idiosync. risk (Huggett-Aiyagari) + gross flows (McFadden)

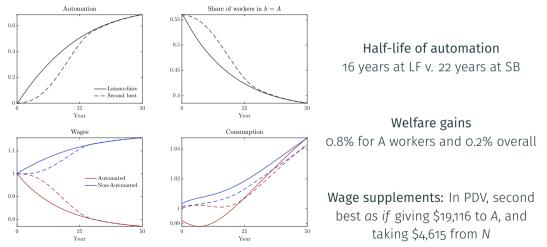
► Adds: gradual autom. + idiosync. risk (Huggett-Aiyagari) + gross flows (McFadden)



► Adds: gradual autom. + idiosync. risk (Huggett-Aiyagari) + gross flows (McFadden)



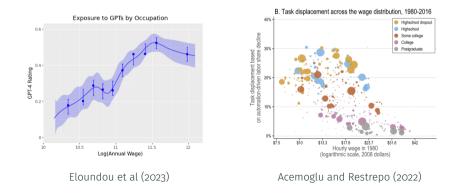
► Adds: gradual autom. + idiosync. risk (Huggett-Aiyagari) + gross flows (McFadden)



# $ROBOTS \neq AI$ (generative, LLMs)

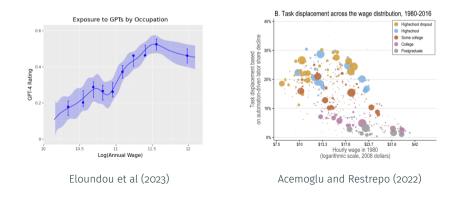
# Robots $\neq$ AI (generative, LLMs)

- **Equity** rationale seems much weaker for AI than it was for robots
  - Robots automate routine, low-to-middle-wage jobs (car manuf)
  - Al (likely) automates cognitive, middle-to high-wage jobs (lawyers, journos, soft devs)



# Robots $\neq$ AI (generative, LLMs)

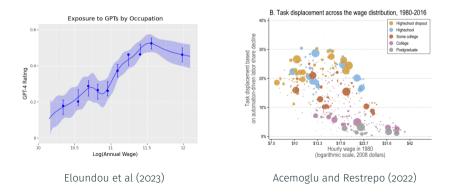
- Efficiency rationale seems much weaker too
  - Lawyers, journos, and soft devs not the first that come to mind as "financially vulnerable"
  - Call centers? College debt?



# Robots $\neq$ AI (generative, LLMs)

- Efficiency rationale seems much weaker too
  - Lawyers, journos, and soft devs not the first that come to mind as "financially vulnerable"
  - ► Call centers? College debt?

► Weaker rationale for **slowing down AI** due to job automation. AI **alignment** concerns?



- ► AI is a new technology with many different features and uses
- ▶ Touches on issues across fields: macro (growth, innovation, labor), pol. econ, IO

- ► AI is a new technology with many different features and uses
- ► Touches on issues across fields: macro (growth, innovation, labor), pol. econ, IO
- ▶ We have a **responsibility** to study the benefits, risks, and policy implications of AI
  - Otherwise, we leave the task to...
- We have only started to scratch the surface. More questions as AI is widely adopted.